

An explicit finite difference scheme for solving the space fractional nonlinear Schrödinger equation

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(Received August 01, 2021, accepted October 09, 2021)

Abstract: This paper uses the finite difference method to numerically solve the space fractional nonlinear Schrödinger equation. First, we give some properties of the fractional Laplacian Δ_h^α . Then we construct a numerical scheme which satisfies the mass conservation law without proof and the scheme's order is $O(\tau^2 + h^2)$ in the discrete L^∞ norm. Moreover, The scheme conserves the mass conservation and is unconditionally stable about the initial values. Finally, this article gives a numerical example to verify the relevant properties of the scheme.

Keywords: Partial Differential Equations; Finite difference method; Numerical solutions

1. Introduction

We consider the space fractional nonlinear Schrödinger equation (SFNLS) equation

$$i \frac{\partial u(x, t)}{\partial t} - (-\Delta)^{\frac{\alpha}{2}} u(x, t) + \beta |u(x, t)|^2 u(x, t) = 0, \quad x \in (a, b), \quad t \in (0, T], \quad (1.1)$$

with boundary condition

$$u(a, t) = u(b, t) = 0, \quad t \in (0, T], \quad (1.2)$$

and initial condition

$$u(x, 0) = u_0(x), \quad x \in [a, b], \quad (1.3)$$

where $1 < \alpha \leq 2$, $i = \sqrt{-1}$ is the complex unit, $u = u(x, t)$ is the unknown complex-valued function, $u_0 = u_0(x)$ is a given smooth complex-valued function, and β is a given non-zero real number. When $\alpha = 2$, the SFNLS equation is reduced into the standard cubic nonlinear Schrödinger equation. Here the fractional Laplacian $-(-\Delta)^{\frac{\alpha}{2}}$ is defined as a pseudo-differential operator with $|\xi|^\alpha$ in Fourier space[8], i.e.,

$$-(-\Delta)^{\frac{\alpha}{2}} u(x, t) = -\mathcal{F}^{-1}(|\xi|^\alpha \hat{u}(\xi, t)), \quad (1.4)$$

where \mathcal{F} is the standard Fourier transform and $\hat{u}(\xi, t) = \mathcal{F}[u(x, t)]$.

2. Construction of Scheme

In this section, we will construct a finite difference scheme for the system (1.1)-(1.3), which preserves the total mass given in **Theorem 2.1**. For given positive integers J, N , we set the time step $\tau = \frac{T}{N}$ and grid size $h = \frac{b-a}{J}$. Denote the space and time discrete node sets by $\Omega_h = \{x_j | x_j = a + jh, 0 \leq j \leq J\}$ and $\Omega_\tau = \{t_n | t_n = n\tau, 0 \leq n \leq N\}$. Then the space and time grid point set is defined by $\Omega_h^\tau = \Omega_h \times \Omega_\tau$. Denote $\mathcal{S}_h = \{u | u = (u_0, u_1, u_2, \dots, u_J), u_0 = u_J = 0\}$ as a grid function space. For any grid function $w^n \in \mathcal{S}_h$ for $n = 1, 2, \dots, N-1$, we introduce the following notations

$$\delta_t w_j^n := \frac{w_j^{n+1} - w_j^{n-1}}{2\tau}, \quad \delta_t w_j^n := \frac{w_j^{n+1} - w_j^n}{\tau}, \quad w_j^{n+\frac{1}{2}} := \frac{w_j^{n+1} + w_j^n}{2}, \quad w_j^{[n]} := \frac{w_j^{n+1} + w_j^{n-1}}{2}. \quad (2.1)$$

for any grid functions $w, v \in \mathcal{S}_h$, we define the discrete inner product and the two norms over \mathcal{S}_h as

$$(v, w) := h \sum_{j=1}^{J-1} v_j \bar{w}_j, \quad |v| := \sqrt{(v, v)}, \quad |v|_\infty := \sup_{1 \leq j \leq J-1} |v_j|. \tag{2.2}$$

Lemma 2.1[11] For a function $\phi \in C^5(R) \cap L^1(R)$, we have

$$\frac{\partial^\alpha \phi(x)}{\partial |x|^\alpha} = -\frac{1}{h^\alpha} \sum_{k=-\infty}^{+\infty} c_k^{(\alpha)} \phi(x - kh) + O(h^2), \quad \forall 1 < \alpha \leq 2, \tag{2.3}$$

where $c_k^{(\alpha)} := \frac{(-1)^k \Gamma(\alpha+1)}{\Gamma(\frac{\alpha}{2}-k+1)\Gamma(\frac{\alpha}{2}+k+1)}$.

According to the initial value of the original equation and the above lemma, we have

$$\frac{\partial^\alpha u(x, t)}{\partial |x|^\alpha} = -\frac{1}{h^\alpha} \sum_{k=-\frac{(b-x)}{h}}^{-\frac{(a-x)}{h}} c_k^{(\alpha)} u(x - kh, t) + O(h^2), \tag{2.4}$$

and

$$-(-\Delta)^{\frac{\alpha}{2}} u_j^n = -\frac{1}{h^\alpha} \sum_{k=-J+j}^j c_k^{(\alpha)} u_{j-k}^n + O(h^2) = -\frac{1}{h^\alpha} \sum_{k=1}^{J-1} c_{j-k}^{(\alpha)} u_k^n + O(h^2). \tag{2.5}$$

For the sake of brevity, we denote

$$\Delta_h^\alpha u_j^n = \frac{1}{h^\alpha} \sum_{k=1}^{J-1} c_{j-k}^{(\alpha)} u_k^n, \quad 1 \leq j \leq J-1, \quad 0 \leq n \leq N, \tag{2.6}$$

and denote matrix \mathbf{C} as

$$\mathbf{C} = \begin{pmatrix} c_0^{(\alpha)} & c_{-1}^{(\alpha)} & \cdots & c_{-J+2}^{(\alpha)} \\ c_1^{(\alpha)} & c_0^{(\alpha)} & \cdots & c_{-J+3}^{(\alpha)} \\ \vdots & \vdots & \ddots & \vdots \\ c_{j-2}^{(\alpha)} & c_{j-3}^{(\alpha)} & \cdots & c_0^{(\alpha)} \end{pmatrix} \tag{2.7}$$

The eigenvalues of the real positive Toeplitz matrix \mathbf{C} is denoted by λ_j for $1 \leq j \leq J-1$ and we have [12]

$$0 < \lambda_j < 2c_0^{(\alpha)}, \quad j = 1, 2, \dots, J-1. \tag{2.8}$$

The scheme of the equation (1.1)-(1.3) constructed in this paper is

$$i\delta_t U_j^n - \Delta_h^\alpha U_j^n + \beta |U_j^n|^2 U_j^n = 0, \quad 1 \leq j \leq J-1, \quad 1 \leq n \leq N-1, \tag{2.9}$$

$$i\delta_t U_j^{\frac{1}{2}} - \Delta_h^\alpha U_j^{\frac{1}{2}} + \beta \left| \hat{U}_j^{\frac{1}{2}} \right|^2 U_j^{\frac{1}{2}} = 0, \quad 1 \leq j \leq J-1, \tag{2.10}$$

$$U_j^0 = u_0(x_j), \quad 1 \leq j \leq J-1, \tag{2.11}$$

$$U_0^n = U_j^n = 0, \quad 1 \leq n \leq N, \tag{2.12}$$

where $U_j^{\frac{1}{2}} = u(x_j, 0) + \frac{\tau}{2} u_t(x_j, 0)$, $1 \leq j \leq J-1$.

Theorem 2.1 The above scheme (2.9)-(2.12) satisfies the following mass conservation

$$M^n := \frac{1}{2} (|U^n|^2 + |U^{n+1}|^2) \equiv M^0, \quad 0 \leq n \leq N-1. \tag{2.13}$$

3. Numerical Experiment

In this section, we use our scheme to compute one numerical example to show our theoretical results.

Example 3.1 We consider the following SFNLS equation

$$i \frac{\partial u(x, t)}{\partial t} - (-\Delta)^{\frac{\alpha}{2}} u(x, t) + \beta |u(x, t)|^2 u(x, t) = 0, \quad a < x < b, \quad 0 < t \leq T, \quad (3.1)$$

with homogeneous Dirichlet boundary conditions and the following initial condition

$$u(x, 0) = \operatorname{sech}(x) \cdot \exp(2ix), \quad a \leq x \leq b. \quad (3.2)$$

For this problem, we take $\alpha = 2, \beta = 2$, and the exact solution is given by

$$u(x, t) = \operatorname{sech}(x - 4t) \cdot \exp(i(2x - 3t)). \quad (3.3)$$

In this example, we set the interval $[a, b] = [-20, 20], M^n$ is the discrete total mass at $t_n = n\tau$.

Table 1: Convergence test for $1 < \alpha \leq 2$ with $\tau = 0.04h$.

α	error	$h = 0.2$	$h = 0.1$	order
1.2	$\ e^N\ _{\infty}$	1.6945e-01	4.4717e-02	1.92
1.4	$\ e^N\ _{\infty}$	2.4276e-01	5.0584e-02	2.26
1.8	$\ e^N\ _{\infty}$	1.8285e-01	4.0860e-02	2.16
2.0	$\ e^N\ _{\infty}$	1.4267e-01	3.4243e-02	2.06

Table 1 gives the errors together with the corresponding orders of numerical solutions in the maximum norm at $T = 1$, and shows the convergence order in time and space direction for $1 < \alpha \leq 2$. For the exact solution of the equation when $1 < \alpha < 2$, this paper uses the numerical accurate solution to replace it, i.e., we take $h = 0.025, \tau = 1e - 04$ to get a ‘numerical exact’ solution.

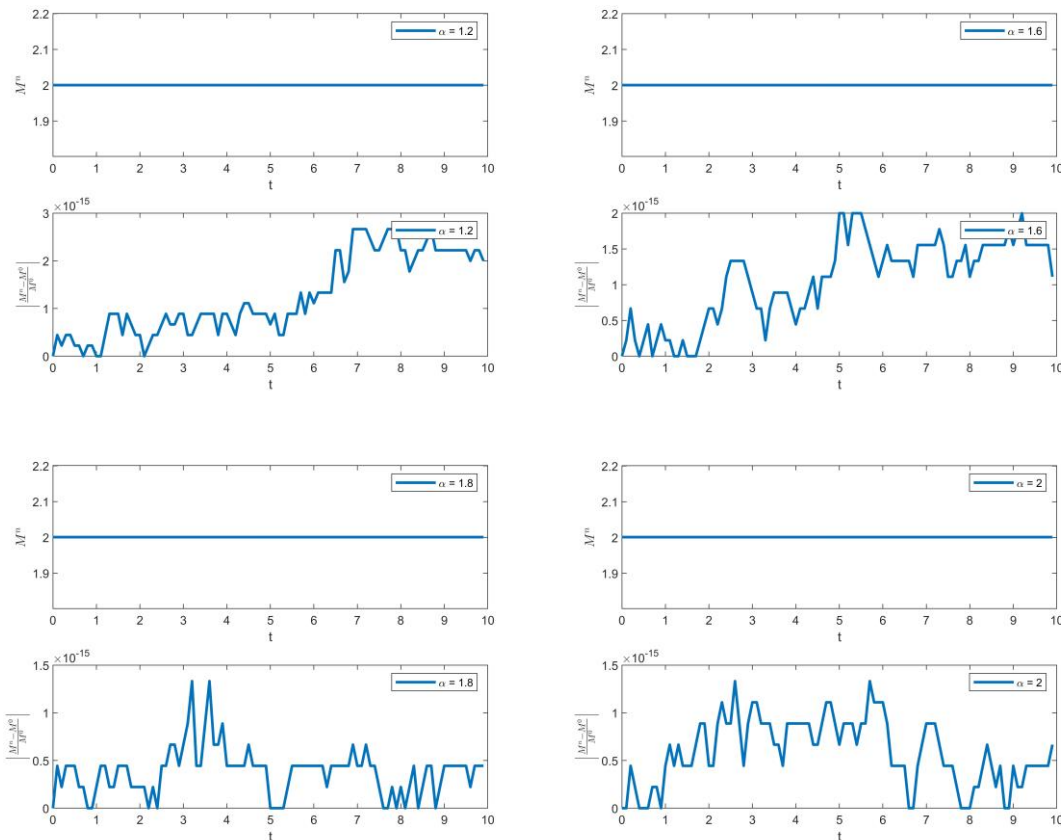


Figure 1: Mass conservation law and its errors for different α by $[a, b] = [-20, 20], T = 10, h = 0.1, \tau = 0.1$.

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